PQHS 471 Lecture 6: Decision Tree, Bayes Classifier, KNN

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Here the response variable Y is qualitative – e.g. email is one of $\mathcal{C} = (\text{spam, ham})$ (ham=good email), digit class is one of $C = \{0, 1, \ldots, 9\}$. Our goals are to:

- Build a classifier $C(X)$ that assigns a class label from C to a future unlabeled observation X .
- Assess the uncertainty in each classification
- Understand the roles of the different predictors among $X = (X_1, X_2, \ldots, X_n).$

Motivating example

Fruit Identification.

"At the edge of the world, statistical journey be[gin](#page-1-0)[s."](#page-3-0)

A flowchart tree-like structure that is made from training set.

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- The method of learning the decision trees from the training set.
- Need to have a training dataset with **observations** and **class labels**.
- The tree structure has a root node, internal nodes or decision nodes, leaf node, and branches.
- The root node is the topmost node. It represents the best attribute selected for classification.
- Internal nodes of the decision nodes represent a test of an attribute of the dataset
- Leaf node or terminal node represents the classification or decision label.
- Some decision trees only have binary nodes (have exactly two branches of a node), while some are non-binary.

Decision Tree Induction: An example

Q Training data set: Buys computer \Box Resulting tree:

age $5 = 30$

 $5 = 30$

high

high

income student credit rating buys computer

excellent

no

 no

fair no

no

- ID3 (Iterative Dichotomiser), C4.5,by Quinlan.
- CART (Classification and Regression Trees)
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- CART (Classification and Regression Trees)
- Basic algorithm (a greedy algorithm)
	- Tree is constructed in a top-down recursive divide-and-conquer manner
	- At start, all the training examples are at the root
	- Attributes(predictors) are categorical (if continuous-valued, they are discretized in advance)
	- Examples are partitioned recursively based on selected attributes
	- Test attributes are selected on the basis of a heuristic or statistical measure (e.g., information gain)

Conditions for stopping partitioning

- All samples for a given node belong to the same class
- \bullet There are no remaining attributes for further partitioning majority **voting** is employed for classifying the leaf
- There are no samples left
- • Idea: select attribute that partition samples into homogeneous groups
- **O** Measures:
	- Information gain (ID3)
	- Gain ratio (C4.5)
	- Gini index (CART)
	- Variance reduction for continuous target variable (CART)

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Brief Review of Entropy

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- Entropy (Information Theory)
	- A measure of uncertainty associated with a random variable
	- Calculation: For discrete random variable Y taking m distinct values $y_1, y_2, ..., y_m$

$$
H(Y) = -\sum_{i=1}^{m} p_i log(p_i)
$$

where $p_i = P(Y = y_i)$

- **·** Interpretation:
	- Higher entropy \rightarrow higher uncertainty
	- Lower entropy \rightarrow lower uncertainty
- Conditional Entropy: $H(Y|X) = \sum_x p(x) H(Y|X=x)$ $H(Y|X) = \sum_x p(x) H(Y|X=x)$

Attribute selection measure: Information Gain (ID3/C4.5)

- Idea: select the attribute with the highest information gain
- Let p_i be the probability that an arbitrary tuple (observation $+$ label) in D belongs to class C_i , estimated by $\vert C_{i,D}\vert/\vert D\vert$
- Expected information (entropy) needed to classify a tuple in D:

$$
Info(D) = -\sum_{i=1}^{m} p_i log(p_i)
$$

• Information needed (after using A to split D into v partitions) to classify D :

$$
Info_A(D) = \sum_{j=1}^{v} \frac{|D_j|}{|D|} \times Info(D_j)
$$

• Information gained by branching on attribute A:

$$
Gain(A) = Info(D) - Info_A(D)
$$

Attribute selection: Information Gain

- Class P: buys computer $=$ "yes"
- Class N: buys computer $=$ "no" $Info(D) = I(9, 5) = -\frac{9}{15}$ $\frac{9}{14} log(\frac{9}{14})$ $\frac{9}{14})-\frac{5}{14}$ $rac{5}{14}log(\frac{5}{14})$ $\frac{8}{14}$) = 0.940

Attribute selection: Information Gain

$$
Info_{age}(D) = \frac{5}{14}I(2,3) + \frac{4}{14}I(4,0) + \frac{5}{14}I(3,2) = 0.694
$$

Here, we have $\frac{5}{14}I(2,3)$ because the "age≤30" group has 5 out of 14 samples, with 2 yes and 3 no.
Hence:

$$
Gain(age) = Info(D) - Info_{age}(D) = 0.246
$$

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Similarly:

 $Gain(age) = 0.246$ $Gain(income) = 0.029$ $Gain(student) = 0.151$ $Gain(credit rating) = 0.048$

Use "age" as the first(root) node for Decision Tree

Computing information gain for continuous valued attributes

- \bullet Let attribute A be a continuous-valued attribute
- \bullet Must determine the best split point for A
	- Sort the value A in increasing order
	- Typically, the midpoint between each pair of adjacent values is considered as a possible split point $\star (a_i + a_{i+1})/2$ is the midpoint between the values of a_i and a_{i+1}
	- \bullet The point with the minimum expected information requirement for A is selected as the split-point for A
- Split: D1 is the set of tuples in D satisfying $A \leq$ split-point, and D2 is the set of tuples in D satisfying $A >$ split-point

Gain Ratio for attribute selection (C4.5)

- Information gain measure is biased towards attributes with a m. large number of values
- \blacksquare C4.5 (a successor of ID3) uses gain ratio to overcome the problem (normalization to information gain)

$$
SplitInfo_{A}(D) = -\sum_{j=1}^{v} \frac{|D_{j}|}{|D|} \times log_{2}(\frac{|D_{j}|}{|D|})
$$

- **EX.** SplitInfo_{income} (D) = $-\frac{4}{14} \times \log_2(\frac{4}{14}) \frac{6}{14} \times \log_2(\frac{6}{14}) \frac{4}{14} \times \log_2(\frac{4}{14}) = 1.557$
	- **gain** ratio(income) = $0.029/1.557 = 0.019$
- \blacksquare The attribute with the maximum gain ratio is selected as the splitting attribute

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Gini Index (CART, IBM IntelligentMiner)

If a dataset D contains examples from n classes, gini index, $qini(D)$ is defined as:

$$
gini(D) = 1 - \sum_{j=1}^{n} p_j^2
$$

where p_i is the relative frequency of class j in D

If a dataset D split on A into two subsets D_1 and D_2 , the gini index $qini(D)$ is defined as:

$$
gini_A(D) = \frac{|D_1|}{|D|}gini(D_1) + \frac{|D_2|}{|D|}gini(D_2)
$$

• Reduction in Impurity:

$$
\Delta gini(A) = gini(D) - gini_A(D)
$$

The attribute provides the largest reduction in impurity (or smallest $qini_{split}(D)$) is chosen to split the node イロト イ押ト イヨト イヨト 2040

Computation of Gini Index

- Ex. D has 9 tuples in buys_computer = "yes" and 5 in "no" gini(D) = $1 - \left(\frac{9}{14}\right)^2 - \left(\frac{5}{14}\right)^2 = 0.459$ Suppose the attribute income partitions D into 10 in D₁: {low,
medium} and 4 in D₂ gini_{ncome(low,medium)} (D) = $\left(\frac{10}{14}\right)$ Gini(D₁) + $\left(\frac{4}{14}\right)$ Gini(D₂) $=\frac{10}{14}\left(1-\left(\frac{7}{10}\right)^2-\left(\frac{3}{10}\right)^2\right)+\frac{4}{14}\left(1-\left(\frac{2}{4}\right)^2-\left(\frac{2}{4}\right)^2\right)$ $= 0.443$ $= Gini_{income \in \{high\}}(D).$
	- $\overline{\textsf{Gini}}_{\{\textsf{low,high}\}}$ is 0.458; $\overline{\textsf{Gini}}_{\{\textsf{medium,high}\}}$ is 0.450. Thus, split on the {low, medium} (and {high}) since it has the lowest Gini index

These three measures, in general, return good results but

• Information Gain:

biased towards multivalued attributes

Gain Ratio:

tends to prefer unbalanced splits in which one partition is much smaller than the others

Gini Index:

(1) biased to multivalued attributes

(2) tends to favor tests that result in equal-sized partitions and purity in both partitions

Overfitting in DTI

Overfitting: An induced tree may overfit the training data

- Too many branches, some may reflect anomalies and noises
- Poor accuracy for unseen sample

Underfitting: when model is too simple, both training and test errors are large

Would you survive the Titanic?

Build a predictive model: "what sorts of people were more likely to イロト イ部 トイヨ トイヨト

Bayes Classification Methods

• The most fundamental statistical classifier.

- Performs probabilistic prediction, i.e., predicts class membership probabilities.
- Foundation: Bayes' Theorem
- The best classifier as it minimizes the expected classification error rate.
- Often used as a reference in simulation study.
- **•** Bayes classifier is often **unknown in practice**.

Total Probability Theorem

 $P(B) = \sum_{i=1}^{M} P(B|A_i) P(A_i)$

Bayes' Theorem

 $P(A|B) = \frac{P(B|A)P(A)}{P(B)}$

- \bullet $P(A|B)$ and $P(B|A)$ are conditional probabilities.
- \bullet $P(A)$ and $P(B)$ are marginal probabilities.

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Posterior \propto Likelihood \times Prior

$$
p(\theta|x) = \frac{p(x|\theta)p(\theta)}{p(x)}
$$

$$
p(\theta|x) \propto p(x|\theta)p(\theta)
$$

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 $p(\theta)$ is the prior $p(x|\theta)$ is the likelihood $p(\theta|x)$ is the posterior

Bayes' theorem: cookie example

$$
P(A|B) = \frac{P(B|A)P(A)}{P(B)}
$$

Red jar: 10 chocolate $+$ 30 plain Yellow jar: 20 chocolate $+$ 20 plain Pick a jar, and then pick a cookie If it's a plain cookie, what's the probability the cookie was picked out of red jar?

Classification using posterior

- \bullet Let D be a training set of tuples and their associated class labels, and each tuple is represented by an $n - D$ attribute vector $X = (x_1, x_2, ..., x_n)$
- Suppose there are m classes $C_1, C_2, ..., C_m$.
- \bullet Classification is to find the *i* s.t.

$$
argmax_{i} P(C_{i}|\mathbf{X})
$$

By Bayes' theorem:

$$
P(C_i|\mathbf{X}) = \frac{P(\mathbf{X}|C_i)P(C_i)}{P(\mathbf{X})}
$$

• Since $P(X)$ is constant for all classes:

 $P(C_i|\mathbf{X}) \propto P(\mathbf{X}|C_i)P(C_i)$

A simplified assumption: attributes are conditionally independent:

$$
P(\mathbf{X}|C_i) = \prod_{k=1}^{n} P(x_k|C_i)
$$

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Class:

C1:buys_computer = 'yes' C2:buys computer = 'no'

Data to be classified: $X = (age \le 30,$ Income = medium, Student = yes Credit_rating = Fair)

(Na¨ıve) Bayes Classifier: Example

Compute $P(X|C_i)$ for each class

P(age = "<=30" | buys computer = "yes") = $2/9$ = 0.222 P(age = "<= 30" | buys_computer = "no") = $3/5$ = 0.6 P(income = "medium" | buys computer = "yes") = $4/9$ = 0.444 P(income = "medium" | buvs computer = "no") = $2/5$ = 0.4 P(student = "yes" | buys computer = "yes) = $6/9$ = 0.667 P(student = "yes" | buys_computer = "no") = $1/5$ = 0.2 P(credit rating = "fair" | buys computer = "yes") = $6/9$ = 0.667 P(credit_rating = "fair" | buys_computer = "no") = $2/5$ = 0.4

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 $X = (age \le 30)$, income = medium, student = yes, credit rating = fair) $P(X|C_i): P(X|$ buys_computer = "yes") = 0.222 x 0.444 x 0.667 x 0.667 = 0.044

 $P(X|$ buys_computer = "no") = 0.6 x 0.4 x 0.2 x 0.4 = 0.019 $P(X|C_i)*P(C_i): P(X|$ buys_computer = "yes") * P(buys_computer = "yes") = 0.028 $P(X | buys_{\text{counter}} = "no") * P(buys_{\text{computer}} = "no") = 0.007$ Therefore, X belongs to class ("buys_computer = yes")

Avoiding the Zero-Probability Problem

• Naïve Bayes Classifier requires each conditional probability to be non-zero. Otherwise, the predicted prob. will be 0:

$$
P(\mathbf{X}|C_i) = \prod_{k=1}^{n} P(x_k|C_i)
$$

- E.g. A dataset with 1,000 tuples, income $=$ low $(n = 0)$, income $=$ medium $(n = 990)$, income = low $(n = 10)$.
- Use Laplacian correction
	- Adding 1 to each case $Prob(income=low) = 1/1003$ $Prob(income=medium) = 991/1003$ $Prob(income=high) = 11/1003$
- The "corrected" prob. estimates are close to their "uncorrected" counterparts.

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Advantages:

- Easy to implement
- Good results obtained in most of the cases

Disadvantages:

- Assumption: class conditional independence, therefore loss of accuracy
- **•** Practically, dependencies exist among variables E.g., hospitals: patients: Profile: age, family history, etc. Symptoms: fever, cough etc.,
- Dependencies among these cannot be modeled by Naïve Bayes Classifier

How to deal with these dependencies? Bayesian Belief Networks

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Predict whether this person will play golf or not for the following tuple: $(Outlook = Sunny, Temp = Cool, Humidity = High, Windy = True)$

 k -nearest neighbors (KNN)

k -nearest neighbors (KNN)

KNN is a local non-parametric classification method.

 k is a hyperparameter.

KNN example with $k = 3$.

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- Given a positive integer k and a test observation x_0
- \bullet First, identifies the k points in the training data that are closest to x_0 , represented by \mathcal{N}_0 .
- \bullet Then, estimates the conditional probability for class i as the fraction of points in \mathcal{N}_0 whose response values equal j.

$$
Pr(Y = j | X = x_0) = \frac{1}{K} \sum_{i \in \mathcal{N}_0} I(y_i = j)
$$

• Assign x_0 to the class with the largest probability.

k -nearest neighbors (KNN)

 $KNN: K=10$

 $X_{\mathbf{1}}$

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\overline{k} -nearest neighbors (KNN)

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